

DECLARATION OF CONFORMITY

According to the Electromagnetic Compatibility Regulations 2016.

Manufacturer	SEIKO EPSON CORPORATION	www.epson.com	
Address	3-5, Owa 3-chome, Suwa-shi	Telephone	+81-266-52-3131
	Nagano-ken 392-8502 Japan	Fax	+81-266-52-8409

Representative	Epson (U.K.) Limited	www.epson.co.uk	
Address	Westside, London Road, Hemel	Telephone	+44-1442-261144
	Hempstead, Hertfordshire, HP3 9TD,		
	United Kingdom		

Declares under our sole responsibility that the product:

Brand Name EPSON

Product Name Robot Controller

Model R114x(x=A or B)(RC700-E) (Serial number $R7E^{***}0001 - R7E^{***}9999$)

<Note> * : 0 - 9, A - Z

For more details, please refer to the product description

Options

See Technical Data File

Conforms to the following Directive(s) and harmonized Norm(s) are applied:

Electromagnetic Compatibility (EMC) 2014/30/EU

EN 55011 2016/A1:2017/A11:2020 Group1 Class A

EN 61000-6-2 2005

EN 61000-6-4 2007/A1:2011

EN 61000-6-7 2015

Restriction of the use of certain hazardous substances (RoHS)2011/65/EU (except options)

EN IEC 63000

Supplementary Information

The year in which the UKCA marking was affixed, is

2023

1st Nov. 2023 Nagano-ken, Japan

Hiroyuki Ozawa

MS CS Quality Assurance Department

General Manager

SEIKO EPSON CORPORATION

Declared based on "Technical Data File,

1st Nov. 2023

AE1461-UKCA02





DECLARATION OF INCORPORATION OF PARTLY COMPLETED MACHINERY

According to Supply of Machinery (Safety) Regulations 2008, SCHEDULE2, PART2, sector 1.B. for a partly completed machinery.

Manufacturer	SEIKO EPSON CORPORATION	www.epson.com	
Address	3-5, Owa 3-chome, Suwa-shi	Telephone	+81-266-52-3131
	Nagano-ken 392-8502 Japan	Fax	+81-266-52-8409
Representative	Epson (U.K.) Limited	www.epson.co.uk	
Address	Westside, London Road, Hemel	Telephone	+44-1442-261144

Declares under our sole responsibility that the product:

Brand Name EPSON

Product Name Industrial Robot/ Robot Controller Model GX4-B,GX8-B,GX10-B,GX20-B

United Kingdom

GX4-B,GX8-B,GX10-B,GX20-B (Serial number G*****0001 - G****9999) R114x(x=A or B)(RC700-E) (Serial number R7E***0001 - R7E***9999)

<Note> * : 0 - 9, A - Z

For more details, please refer to the product description

Options

See Technical Data File

fulfil(s) the basic requirements of the Supply of Machinery (Safety) Regulations 2008 as listed in the attachment to this declaration of incorporation.

The manufacturer undertakes to electronically supply the relevant technical documentation, referred to in Part7 sector B for the partly completed machinery, to national authorities upon reasoned request.

This partly completed machine must not be put into service until the machinery into which it is to be incorporated, has been declared in conformity with the provisions of the Machinery (Safety) Regulations.

Furthermore this partly completed machinery fulfils all relevant provisions of the directive:

- Electromagnetic Compatibility Regulations 2016
- The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012 (except options)

Following harmonized norms and specifications are applied:

Safety:			EMC:	
EN ISO 10218-1 2011	IEC 61508-1 201	010	EN 55011	2016/A1:2017/A11:2020 Group1 Class A
EN ISO 12100 2010	IEC 61508-2 201)10	EN 61000-6-2	2005
EN 60204-1 2018	IEC 61508-3 201	010	EN 61000-6-4	2007/A1:2011
EN ISO 13850 2015			EN 61000-6-7	2015
EN 61800-5-1 2007/A1:2017	1			
EN 61800-5-2 2017			RoHS:	
EN ISO 13849-1 2015			EN IEC 63000	2018
IEC 62061 2021				

Supplementary Information

The year in which the UKCA marking was affixed, is

2023

1st Nov. 2023 Nagano-ken, Japan

Hiroyuki Ozawa

MS CS Quality Assurance Department

General Manager

SEIKO EPSON CORPORATION

Declared based on "Technical Data File,

1st Nov. 2023 "





Annex to declaration of incorporation of partly completed machinery

for following product(s):

Product Name: Model:

 $\begin{array}{lll} \mbox{Industrial Robot} & \mbox{GX4-B,GX8-B,GX10-B,GX20-B} & (\mbox{Serial number } G^{*****}0001 - G^{*****}9999) \\ \mbox{/ Robot Controller} & \mbox{R114x}(x=A \mbox{ or } B)(RC700-E) & (\mbox{Serial number } R7E^{***}0001 - R7E^{***}9999) \\ \end{array}$

<Note> * : 0 - 9, \hat{A} - Z

The following basic requirements of the **Machinery Directive 2006/42/EC** are applied and will be adhered. Appropriate items to be marked "X".

The Machinery Directive 2006/42/EC, Annex I The Supply of Machinery (Safety) Regulations 2008, Schedule 2, Part 1 - Essential health and safety requirements relating to the design and construction of machinery	Applicable and adhered C:Conform NC:Not conform NA:Not applicable
1. Essential health and safety requirements	-
1.1. General	-
1.1.1. Definitions	-
1.1.2. Principles of safety integration	C
1.1.3. Materials and products used	C
1.1.4. Integral lighting	NA
1.1.5. Handling of machinery and parts of machinery	C
1.1.6. Ergonomic principles	С
1.1.7. Operating positions in hazardous environments	NA
1.1.8. Seating and the provision of seats	NA
1.2. Control systems	-
1.2.1. Safety and reliability of control systems	С
1.2.2. Control devices	С
1.2.3. Control of starting	С
1.2.4. Stop control devices	-
1.2.4.1. Normal stop control devices	С
1.2.4.2. Operational stop	C
1.2.4.3. Emergency stop devices	С
1.2.4.4. Stop controls for assemblies of machinery	C
1.2.5. Mode Selection	C
1.2.6. Failure of the power supply	C
1.3. Protection against mechanical hazards	-
1.3.1. Stability	C
1.3.2. Break-up during operation	C
1.3.3. Falling or ejected objects	С
1.3.4. Sharp edges and angles and rough surfaces	C
1.3.5. Combined machinery	NA
1.3.6. Variations in operating conditions	NA
1.3.7. Moving parts	C
1.3.8. Moving parts	NA
1.3.8.1. Moving transmission parts	NA
1.3.8.2. Moving parts involved in the process	NA

The Machinery Directive 2006/42/EC, Annex I The Supply of Machinery (Safety) Regulations 2008, Schedule 2, Part 1 - Essential health and safety requirements relating to the design and construction of machinery		Applicable and adhered C:Conform NC:Not conform NA:Not applicable
1.3.9.	Uncontrolled movements	C
1.4.	Required characteristics of guards and protective devices	-
1.4.1.	General requirements for guards and protective devices	NA
1.4.2.	Special requirements for guards	-
1.4.	2.1. Fixed guards	NA
1.4.	2.2. Interlocking movable guards	NA
1.4.	2.3. Adjustable guards resticting access	NA
1.4.3.	Protective devices	NA
1.5.	Risks due to other hazards	-
1.5.1.	Electricity	С
1.5.2.	Unwanted static electricity	С
1.5.3.	Energy supply other than electricity	NA
1.5.4.	Errors of fitting	С
1.5.5.	Extreme temperatures	NA
1.5.6.	Fire	С
1.5.7.	Explosion	NA
1.5.8.	Reduction of noise emission	С
1.5.9.	Vibrations	С
1.5.10.	Ionising and non-ionising radiation	С
1.5.11.	External radiation	С
1.5.12.	Laser radiation	NA
1.5.13.	Emissions of hazardous materials and substances	NA
1.5.14.	Risk of being trapped	NA
1.5.15.	Slips, trips and falls	NA
	Lightning	С
1.6.	Maintenance	-
1.6.1.	Maintenance	С
1.6.2.	Access to operating positions and servicing points	С
1.6.3.	Isolation of energy sources	С
1.6.4.	Operator interventions	С
1.6.5.	Cleaning of internal parts	NA
1.7.	Information	-
1.7.1.	Information and warnings / language	С
	1.1. Information and information devices	С
	1.2. Warning devices	NA
1.7.2.	Warning of residual risks	C
1.7.3.	Marking of machinery	C
1.7.4.	Instructions	C
1.7.		C
	4.2. Instruction's content	C



The Suppl	inery Directive 2006/42/EC, Annex I y of Machinery (Safety) Regulations 2008, Schedule 2, Part 1 I health and safety requirements relating to the design and construction inery	Applicable and adhered C:Conform NC:Not conform NA:Not applicable
1.7.4.3.	Sales literature	С
2. gories of	Supplementary essential health and safety requirements for certain cate- f machinery	NA
3.	Supplementary essential health and safety requirements to offset hazards due to the mobility of machinery	NA
4.	Supplementary essential health and safety requirements to offset hazards due to lifting operations	NA
5.	Supplementary essential health and safety requirements for machinery intended for underground work	NA
6. senting	Supplementary essential health and safety requirements for machinery pre- particular hazards due to the lifting of persons	NA

Annex to manipulator type

```
: Series name
                                      GX
a
                                              : 4kg
b
    : Payload
                                       4
                                              : 250mm
    : Arm length
                                       25
c
                                       30
                                              : 300mm
                                       35
                                              : 350mm
    : Axis#3 stroke
                                       1
                                              : 150mm(120mm)
d
                                              * () Is Clean, with bellows option
    : Environment
                                       S
                                              : Standard (equivalent to IP20)
e
                                       E
                                              : Standard(IP20)+ESD
                                       C
                                              : Clean+ESD
f
    : Mounting
                                     None
                                              : Table top mounting
                                              : Multiple mounting
                                       M
    : Cable mounting direction
                                     None
                                              : Standard(Table top mounting -back out, multi-top out)
g
                                       В
                                              : Table top mounting -bottom out
                                     None
                                              : Straight
h
    : Arm type
                                       -L
                                              : Left carving
                                       -R
                                              : Right carving
                                              В
    : Series name
                                      GX
a
b
    : Payload
                                       8
                                              : 8kg
c
    : Arm length
                                       45
                                              : 450mm
                                       55
                                              : 550mm
                                       65
                                              : 650mm
    : Axis#3 stroke
                                       2
                                              : 200 \text{mm} (170 \text{mm})
d
                                       3
                                              : 330 \text{mm} (300 \text{mm})
                                              * () Is Clean, IP, with bellows option
e
    : Environment
                                       S
                                              : Standard (equivalent to IP20)
                                       Е
                                              : Standard(IP20)+ESD
                                       C
                                              : Clean+ESD
                                       P
                                              : Protected(IP65)
                                              : Table top mounting
f
    : Mounting
                                     None
                                       W
                                              : Wall mounting
                                       R
                                              : Ceiling mounting
    : Cable mounting direction
                                              : Standard(Table top mounting -back out, Ceiling mount-
                                     None
g
                                              ing - back out, multi-top out)
                                       В
                                              : Table top mounting -bottom out
```

		\underline{GX} $\underline{10}$ - \underline{B} $\underline{65}$ $\underline{1}$ \underline{S} $\underline{\square}$
		a b c d e f
a	: Series name	GX
b	: Payload	10 : 10kg
c	: Arm length	65 : 650mm
		85 : 850mm
d	: Axis#3 stroke	1 : 180mm(150mm)
		4 : 420mm(390mm)
		* () Is Clean, IP, with bellows option
e	: Environment	S : Standard (equivalent to IP20)
		C : Clean+ESD
		P : Protected(IP65)
f	: Mounting	None : Table top mounting
		W : Wall mounting
		R : Ceiling mounting
		<u>GX 20 - B 85 1 S □</u>
		a b c d e f
a	: Series name	GX
b	: Payload	20 : 20kg
c	: Arm length	85 : 850mm
		A0 : 1000mm
d	: Axis#3 stroke	1 : 180mm(150mm)
		4 : 420mm(390mm)
		* () Is Clean, IP, with bellows option
e	: Environment	S : Standard (equivalent to IP20)
		C : Clean+ESD
		P : Protected(IP65)
f	: Mounting	None : Table top mounting
		W : Wall mounting
		R : Ceiling mounting
Ann	ex to controller type	

: Controller Type A B

: RC700-E FOR GX4 series : RC700-E FOR GX8 series, GX10 series, GX20 series



Annex to hardware options

For industrial robot:	For robot controller:
☐ External Wiring Unit	☐ Expansion I/O
☐Tool Adapter	□ RS-232C
□M/C Cable	☐ Analog I/O
☐ Camera Mounting Bracket	☐ Fieldbus I/O Slave(PROFIBUS-DP, DeviceNET, CC-LINK, Ether-
\square Bellows	Net/IP, PROFINET, EtherCAT)
	☐ Fieldbus I/O Master (PROFIBUS-DP, DeviceNET, EtherNet/IP)
	☐ Teach pendant TP2,TP3
	☐ Emergency stop box, cable
	☐ wall mounting bracket
	☐ PG Board, Conveyor Tracking
	☐ Hot Plug Kit