### **EPSON**

### UK CA

### **DECLARATION OF CONFORMITY**

According to the Electromagnetic Compatibility Regulations 2016.

Manufacturer	SEIKO EPSON CORPORATION	www.epson.com	
Address	3-5, Owa 3-chome, Suwa-shi	Telephone	+81-266-52-3131
	Nagano-ken 392-8502 Japan	Fax	+81-266-52-8409

Representative	Epson (U.K.) Limited	www.epson.co.uk	
Address	Floor 3&4, The Clarendon Works,	Telephone	+44-1442-261144
	37-39 Clarendon Road, Watford		
	WD17 1 IA IJ K		

This declaration of conformity is issued under the sole responsibility of the manufacturer:

Brand Name EPSON

Product Name Robot Controller

Model R114x(x=A or B)(RC700-E) (Serial number  $R7E^{***}0001 - R7E^{***}9999$ )

<Note> \* : 0 - 9, A - Z

For more details, please refer to the product description

Options

See Technical Data File

Conforms to the following Directive(s) and harmonized Norm(s) are applied:

The Electromagnetic Compatibility Regulations 2016

EN 55011 2016/A1:2017/A11:2020 Group1 Class A

EN 61000-6-2 2005

EN 61000-6-4 2007/A1:2011

EN 61000-6-7 2015

The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012

EN IEC 63000 2018

**Supplementary Information** 

The year in which the UKCA marking was affixed, is

2023

27th Aug. 2024 Nagano-ken, Japan

zawa

Hiroyuki Ozawa

MS CS Quality Assurance Department

General Manager

SEIKO EPSON CORPORATION

Declared based on "Technical Data File, 27th

27th Aug. 2024 "

AE1461-UKCA04-C





#### DECLARATION OF INCORPORATION OF PARTLY COMPLETED MACHINERY

According to Supply of Machinery (Safety) Regulations 2008, SCHEDULE2, PART2, sector 1.B. for a partly completed machinery.

Manufacturer	SEIKO EPSON CORPORATION	www.epson.com	
Address	3-5, Owa 3-chome, Suwa-shi	Telephone	+81-266-52-3131
	Nagano-ken 392-8502 Japan	Fax	+81-266-52-8409
Representative	Epson (U.K.) Limited	www.epson.co.uk	
Address	Floor 3&4, The Clarendon Works,	Telephone	+44-1442-261144
	37-39 Clarendon Road, Watford		

This declaration of incorporation is issued under the sole responsibility of the manufacturer.

WD17 1JA, U.K.

Brand Name EPSON

Product Name Industrial Robot/Robot Controller
Model GX4-B,GX8-B,GX10-B,GX20-B

GX4-B,GX8-B,GX10-B,GX20-B (Serial number G\*\*\*\*0001 - G\*\*\*\*9999) R114x(x=A or B)(RC700-E) (Serial number R7E\*\*\*0001 - R7E\*\*\*9999)

<Note> \* : 0 - 9, A - Z

For more details, please refer to the product description

Options

See Technical Data File

Fulfills the following essential health and safety requirements of the Supply of Machinery (Safety) Regulations 2008:

1.1.2, 1.1.3, 1.1.5, 1.1.6, 1.2.1, 1.2.2, 1.2.3, 1.2.4.1, 1.2.4.3, 1.2.5, 1.2.6, 1.3.1, 1.3.2, 1.3.3, 1.3.4, 1.3.6, 1.3.7, 1.3.9, 1.5.1, 1.5.2, 1.5.4, 1.5.6, 1.5.8, 1.5.9, 1.5.10, 1.5.11, 1.6.1, 1.6.2, 1.6.3, 1.6.4, 1.7.1, 1.7.1.1, 1.7.2, 1.7.3, 1.7.4

The manufacturer undertakes to electronically supply the relevant technical documentation, referred to in Part7 sector B for the partly completed machinery, to national authorities upon reasoned request.

This partly completed machine must not be put into service until the machinery into which it is to be incorporated, has been declared in conformity with the provisions of the Machinery (Safety) Regulations.

Furthermore this partly completed machinery fulfils all relevant provisions of the directive:

- Electromagnetic Compatibility Regulations 2016
- The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012 (except options)

Following harmonized norms and specifications are applied:

0		1	11		
Safety:				EMC:	
EN ISO 10218-1	2011	IEC 61508-1	2010	EN 55011	2016/A1:2017/A11:2020 Group1 Class A
EN ISO 12100	2010	IEC 61508-2	2010	EN 61000-6-2	2005
EN 60204-1	2018	IEC 61508-3	2010	EN 61000-6-4	2007/A1:2011
EN ISO 13850	2015			EN 61000-6-7	2015
EN 61800-5-1	2007/A1:201	7			
EN 61800-5-2	2017			RoHS:	
EN ISO 13849-1	2015			EN IEC 63000	2018
IEC 62061	2021				

Supplementary Information

The year in which the UKCA marking was affixed, is

2023

27th Aug. 2024 Nagano-ken, Japan

Hiroyuki Ozawa

MS CS Quality Assurance Department

General Manager

SEIKO EPSON CORPORATION

Declared based on "Technical Data File, 27th Aug. 2024"

\*4144026-04\*

AE1461-UKCA04

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### Annex to manipulator type

		GX a	<u>4</u> b	-	В	25 c	<u>1</u> d	<u>S</u> e	$\frac{\Box}{\mathrm{f}}$	□ g	□ h	i
a	: Series name			(	GΧ							
b	: Payload				4	: 41	ζ					
c	: Arm length				25		50mn	1				
	_				30	: 30	)0mn	1				
					35		50mn					
d	: Axis#3 stroke				1				mm)			
	F '				C				with			•
e	: Environment				S E				quiva		o IP2	0)
					C C		lanua lean+		20)+1	ESD		
f	: Mounting				one				ounti	nσ		
•	. Wounting				M				ountin			
g	: Cable mounting d	irectio	n		one						ountii	ng -back out, multi-top out)
C	8				В				ounti			
h	: Arm type			N	one	: S1	traigh	ıt				
					-L		eft ca					
	<b>T</b> T 1.1				-R		ight o	carvir	ng			
i	: Variation				one		one	٠, ٠,			(0	V4 D251C I 1 )
				/	X5	: F0	or Sp	ecilic	cust	omer	s (G	X4-B351C-L only)
			GX	8	_	В	<u>45</u>	<u>2</u>	S	П	П	
			a	b		D	c	d d	<u>S</u> e	f	<u>□</u> g	
											J	
a	: Series name			(	GΧ							
b	: Payload				8	: 81						
c	: Arm length				45		50mn					
					55		50mn					
.1					65		50mn		· ·			
d	: Axis#3 stroke				2 3				)mm) )mm)			
					3						11000	soption
e	: Environment				S						o IP2	
	Larvironnichi						анца		шиха			
	. Environment								_		- 11	0)
	. Environment				E	: S1		rd(IP	20)+1		. II <b>-</b>	·)
	. Environment					: S1 : C	tanda	rd(IP -ESD	20)+1			<b>o</b> )
f	: Mounting				E C P	: St : C : Pt : Ta	tanda lean+ rotect able t	rd(IP ESD ed(II op m	20)+1 265) ounti	ESD		<b>O</b> )
f					E C P Ione W	: St : C : Pr : Ta : W	tanda lean+ rotect able t Vall m	rd(IP ESD ted(II op m	20)+] P65) ounting	ESD	- II -	<b>O</b> )
	: Mounting	. ,.			E C P one W R	: St : C : Pt : Ta : W : C	tanda lean+ rotect able t Vall m eiling	rd(IP ESD ed(II op m ount g mou	20)+1 P65) ountii ing inting	ESD ng		
f g		irectio	n		E C P Ione W	: St : C : Pt : Ta : W : C : St	tanda lean+ rotect able t Vall m eiling tanda	rd(IP ESD ted(II op m tount g mou rd(Ta	20)+l 265) ountiing inting	ESD ng s op mo	ountii	ng -back out, Ceiling mount-
	: Mounting	irectio	n	N	E C P one W R	: St : C : Pt : Ta : W : C : St ing	tanda lean+ rotectable t Vall m eiling tanda - bad	rd(IP ESD ted(II top m tount g mou rd(Ta	20)+1 P65) ountii ing inting	ESD  ng  s  op mo lti-top	ountii	ng -back out, Ceiling mount-

## **EPSON**

		GX a	<u>10</u> b	-	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
		а	U		c u c i
a	: Series name		GX		
b	: Payload		10		: 10kg
c	: Arm length		65		: 650mm
			85		: 850mm
d	: Axis#3 stroke		1		: 180mm(150mm)
			4		: 420mm(390mm)
					* () Is Clean,IP, with bellows option
e	: Environment		S		: Standard (equivalent to IP20)
			C		: Clean+ESD
			P		: Protected(IP65)
f	: Mounting		None		: Table top mounting
			W		: Wall mounting
			R		: Ceiling mounting
		<u>GX</u>	<u>20</u>		<u>B</u> 85 <u>1</u> <u>S</u> □
		a	<u>20</u> b	-	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
		а	υ		c d e i
a	: Series name		GX		
b	: Payload		20		: 20kg
c	: Arm length		85		: 850mm
			A0		: 1000mm
d	: Axis#3 stroke		1		: 180mm(150mm)
			4		: 420mm(390mm)
					* () Is Clean,IP, with bellows option
e	: Environment		S		: Standard (equivalent to IP20)
			C		: Clean+ESD
			P		: Protected(IP65)
f	: Mounting		None		: Table top mounting
			W		: Wall mounting
			R		: Ceiling mounting

### Annex to controller type

a : Controller Type A : RC700-E FOR GX4 series

B : RC700-E FOR GX8 series, GX10 series, GX20 series



### Annex to hardware options

For industrial robot:	For robot controller:
☐ External Wiring Unit	☐ Expansion I/O
☐Tool Adapter	□ RS-232C
□M/C Cable	☐ Analog I/O
☐ Camera Mounting Bracket	☐ Fieldbus I/O Slave(PROFIBUS-DP, DeviceNET, CC-LINK, Ether-
$\square$ Bellows	Net/IP, PROFINET, EtherCAT)
	☐ Fieldbus I/O Master (PROFIBUS-DP, DeviceNET, EtherNet/IP)
	☐ Teach pendant TP2,TP3,TP4
	☐ Emergency stop box, cable
	☐ wall mounting bracket
	☐ PG Board, Conveyor Tracking
	☐ Hot Plug Kit