



4131141-07

EPSON[®]
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DECLARATION OF INCORPORATION OF PARTLY COMPLETED MACHINERY

According to EC machinery directive 2006/42/EC, Annex II, Part 1, sector B for a partly completed machine

Manufacturer:

SEIKO EPSON CORPORATION
3-5, Owa 3-chome, Suwa-shi
Nagano-ken 392-8502
Japan

<http://global.epson.com/company/>

Entity placing on the market:

EPSON Deutschland GmbH,
Mr. Volker Spanier
Otto-Hahn-Straße 4
40670 Meerbusch
Germany
<https://www.epson.eu>

Attorney to compile the relevant technical documentation:

EPSON EUROPE B.V.
Atlas Arena, Asia Building, Hoogoorddreef 5,1101 BA
Amsterdam Zuidoost The Netherlands
Telephone : 31-20-314-5000

The manufacturer undertakes to electronically supply the relevant technical documentation, referred to in Annex VII part B for the partly completed machinery, to national authorities upon reasoned request.

This partly completed machine must not be put into service until the machinery into which it is to be incorporated, has been declared in conformity with the provisions of the Machinery Directive.

The manufacturer/assignee confirms hereby that following product(s):

| Product Name: | Model: | |
|------------------|-----------------------------|---|
| Industrial Robot | LS3 series robots | (Serial number L3**000001 - L3**ZZ9999) |
| | LS6 series robots | (Serial number L6**000001 - L6**ZZ9999) |
| | LS20 series robots | (Serial number L2**000001 - L2**ZZ9999) |
| | LS3-B series robots | (Serial number L3B*000001 - L3B*ZZ9999) |
| | LS6-B series robots | (Serial number L6B*000001 - L6B*ZZ9999) |
| | LS10-B series robots | (Serial number LA**000001 - LA**ZZ9999) |
| | With RC90/RC90-B controller | (Serial number R***000001 - R***ZZ9999) |
| | | <Note> * : 0 - 9, A - Z |

fulfil(s) the basic requirements of the Machinery Directive 2006/42/EC as listed in the attachment to this declaration of incorporation

Furthermore this partly completed machinery fulfils all relevant provisions of the directive:

- Electromagnetic Compatibility (EMC) 2014/30/EU

Following harmonized norms and specifications are applied:

| | | |
|--------------|------------------|--|
| EN 55011 | 2009/A1: 2010 | Industrial, scientific and medical equipment - Radio-frequency disturbance characteristics - Limits and methods of measurement |
| EN 61000-6-2 | 2005/AC: 2005 | Electromagnetic compatibility (EMC) - Part 6-2: Generic standards - Immunity for industrial environments |
| EN ISO 12100 | 2010 | Safety of machinery – General principles for design – Risk assessment and risk reduction (ISO 12100:2010) |

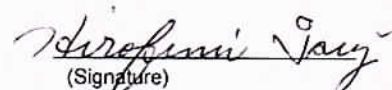
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|----------------|------------------|--|
| EN ISO 10218-1 | 2011 | Robots and robotic devices – Safety requirements for industrial robots – Part 1: Robots (ISO 10218-1:2011) |
| EN ISO 13849-1 | 2015 | Safety of machinery - Safety-related parts of control systems - Part 1: General principles for design |
| EN ISO 13850 | 2015 | Safety of machinery - Emergency stop - Principles for design |
| EN 60204-1 | 2006 /A1:2009 | Safety of machinery - Electrical equipment of machines - Part 1: General requirements |

**Nagano-ken,
22th February 2019**

(Place, Date)

Hirofumi Tsuji
RS CS Quality Assurance Department
General Manager

(Signatory's surname, first name and position)


(Signature)