Experience the power in precision









Compact, fast and extremely versatile

With over 300 variations, arm lengths from 175 mm to 1,000 mm, load capacities from 1 kg up to 20 kg and a range of installation types and protection classes, Epson's range of SCARA robots (Selective Compliance Assembly Robot Arm) provides the high performance and reliability that Epson robots are famous for. Designed for virtually any application and perfect for an economical automation solution.

We are SCARA

Epson has been specialising in SCARA ever since these articulated robots first entered the market. Our robotic systems reflect decades of experience in high-precision micro-component assembly, and are globally recognised for their speed, accuracy, and ease of use. We are also committed to continuous development, such as right and left arm optimisation, ball bearing spindles, Smart Motion control and the invention of the Spider, a unique SCARA robot with no dead zone.

The SCARA principle:

It's no coincidence that SCARA robots have become a success story in automation. They are quick and easy to set up, provide ultra-high speeds, and offer the best-in-class cycle rates and motion range making them ideal for high precision assembly.

SCARA robots have four easily programmable axes which enable manipulation in parallel planar surfaces. Their four degrees of freedom ensures greater freedom of movement, agility and the ability to position and to join heavy payload in each horizontal orientation.

Varying arms lengths & load capacities



How to decode the G-series names

Below is an example to show you how to "read" the names: G6-553 SW.



Example

Payload up to 6kg, 550 mm arm length, 330 mm shaft length, standard design wall mounting G6-553SW

Varying arms lengths & load capacities









Multimount (G3-351SM) ų,

Range of protection classes





IP54 (G6-451D)



G6-651S

Wall (G6-451SW)



IP65 (G6-451P)





ISO3/ESD (G6-451C)

Ceiling (G6-451SR)



The Epson principle: Make great even better

As a specialist in SCARA technology, we continuously optimise every detail for your benefit; offering speed, motion efficiency, high repeatability and ultra-precise path control to ensure maximum productivity in small spaces.

User wiring

Four air supply/vacuum lines 24 signal points Robust and durable Wide range of applications

Integrated wiring harness

Compact and space-saving with fewer interfering contours Reduced mechanical sensitivity Improved ESD shielding

Harmonic Drive Gear

Zero backlash Improved positioning accuracy and repeatability Small size and light weight High reliability and long life

Extended Z-axis for applications that require longer strokes

Epson Smart Motion: Precision brought to the point

Smart Motion delivers greater precision and efficiency. It allows the robots to reach their end positions faster, with greater accuracy and with fewer vibrations. Whatever manufacturing challenges you face, Epson robots get to the point quicker, more precisely and with greater efficiency.







Absolute rotary encoder on all axes

21 bit resolution on one motor revolutionOutstanding joining propertiesSuperior interpolation propertiesHigh precision speed control

Profile in monocoque design2.5 times as stiff as conventional cast aluminium armsHigh insertion forcesOptimised joining properties

Adjustable stops for limiting the motion range

··· Low vibration base

Gentle on products Improved repeatability and absolute accuracy Optimised joining properties

Optional:

Vertical power/signal cable directly under the base Compact, clean and safe in cleanrooms Safe in contaminated environments (IP65 applications)

Compact, space-saving mounting base

Tapped holes for improved reproducibility of the robot's position

A new dimension in SCARA performance

Epson SCARA robots demonstrate strong performance and unsurpassed reliability across a diverse range of applications.

Loading and uploading of machines

Epson SCARA G Series ensures even higher manufacturing quality, speed and precision with exclusive Smart Motion Control technology. Whether loading or unloading on pallets, carriers, conveyor belts, or fed manually, Epson SCARA robots can provide precision tracking for highly productive pick-and-place operation.

Assembly and placement

Epson SCARA robots are ideal for assembly and placement tasks, even for small batches and components; with their excellent dynamics, high insertion force and agile balance of dead weight and payload.

Packaging and palletising

Modern packaging requires a high degree of flexibility, and short changeovers are vital. Epson SCARA robots can package and palletise highly sensitive parts at ultra-fast speed. With Conveyor Tracking, parts on the conveyor belt can be gripped and removed directly by the robot – detected and guided by an integrated camera.

Testing, measuring and inspecting

Epson SCARA robots, along with the integrated Epson image processing system enable quality inspections, accurate measurement and fast test runs prior to production with precise detection – even with short cycle times. If the product's predefined parameters deviate from the tolerance values, the product is detected as faulty at an early stage and can be safely removed.

The high performance controller: Epson RC700-A controller

The Epson RC700-A controller is the next-generation, high performance controller line with power, open architecture and industry-leading ease of use. Capable of standing alone or as an integrated system, the Epson RC700-A is designed to control multiple robots and various peripherals in complex environments. The flexible controller supports both conveyor tracking, as well as various bus protocols and interface extensions.

The integrated Epson Vision Guide 7.0 software enables parts to be reliably detected and positioned – even with manufacturing deviations, varying positions and poor light conditions.



Everything in range, everything in view:

Convenient mobile control and high contrast 10" display with Teach Pendant TP3 ensures ease of use for both right-handed and lefthanded operators.

Fast processors enable sophisticated visualisation and operating applications.



Epson SCARA G1: Powerful yet compact

SCARA G1 robots are suitable for use in the smallest of spaces. They are designed for precision processes with tolerances of thousandths of a millimetre. Such as in electronics production or precision machining processes. Their high-strength aluminium structure makes them ultra-light.

| Epson SCA | RA | G1-171S | G1-221S | G1-171SZ | G1-221SZ | |
|--------------------|---|---|---|---|---|--|
| Design | | Four-axis, outwardly oriented horizontal articulated arm | | Three-axis, outwardly oriented horizontal articulated | | |
| Load capac | sity | 0.5/1 kg n | om./max. | 0.5/1.5 kg n | om./max. | |
| Range | Horizontal (J1+J2) Vertical (J3) Orientation (J4) | 175 mm (75+100) 100/80 mm (cleanroom) +/-360° | 225 mm (125+100) 100/80 mm (cleanroom) +/-360° | 175 mm (75+100) 100/80 mm (cleanroom) – | 225 mm (125+100) 100/80 mm (cleanroom) – | |
| Repeata- bility | Horizontal (J1+J2) Vertical (J3) Orientation (J4) | +/-0.005 mm +/-0.01 mm +/-0.01° | +/-0.008 mm +/-0.01 mm +/-0.01° | +/-0.005 mm +/-0.01 mm - | +/-0.008 mm +/-0.01 mm - | |
| Moment of inertia | | 0.0003/0.004 kg m ² nom./max. | 0.0003/0.004 kg m ² nom./max. | - | - | |
| User cabling | g | Electrical: connections for 1x 15-pin and 1x 9-pin D-Sub connectors Pneumatic: connections for compressed air supply (1 x \emptyset 4 mm and 2 x \emptyset 6 mm) | | | | |
| Z-axis | | Ø 8 mm, H 7 mm | | | | |
| Insertion force | | Permanent 50 (N) | | | | |
| Weight | | 8 kg | | | | |
| Controller | | RC700-A | | | | |
| Manipulator design | | Mounting option for floor, cleanroom (ISO3) & ESD | | | | |
| Available op | otions | Exten | ded power and signal cable | e (5 m / 10 m / 20 m), bellov | WS | |

What's included:

Epson robot and controller Epson RC+ program CD including simulator Mounting bracket for the robot controller 70g grease for Z-axis 3m motor and signal cable Plug for emergency stop Plug for standard inputs and outputs Plug set for user cabling USB programming cable CD Manuals Installation/safety manual

Manipulator options:

Extended power and signal cable (5m/10m/20m)

Bellows option for mounting on Z-axis to protect the spindle and the environment from contamination



Epson SCARA G1 dimensions

Side view

| | G1-171S | G1-221S | G1-171SZ | G1-221SZ |
|---|-------------|--------------------|----------------------|-------------|
| | 4-axis | 4-axis | 3-axis | 3-axis |
| | Outv | wardly oriented ho | rizontal articulated | arm |
| А | 75 mm | 125 mm | 75 mm | 125 mm |
| В | 515 mm max. | 545 mm max. | 515 mm max. | 545 mm max. |



Working range Epson SCARA G1

| | G1-171S G1-221S | | G1-171SZ | G1-221SZ |
|-----|-----------------|--------------------|----------------------|----------|
| | 4-axis | 4-axis | 3-axis | 3-axis |
| | Outv | vardly oriented ho | rizontal articulated | arm |
| а | 75 mm | 125 mm | 75 mm | 125 mm |
| b-a | 100 mm | 100 mm | 100 mm | 100 mm |
| С | 64,3 mm | 59,6 mm | 70,9 mm | 89,2 mm |
| d | 125° | 125° | 125° | 125° |
| е | 140° | 152° | 135° | 135° |
| f | 60,4 mm | 52,8 mm | 69,2 mm | 82,2 mm |

- a Length of the 1st arm b Length of the 2nd arm
- d Working range of the 1st axis
- c Working range
- e Working range of the 2nd axis

- f Range of the mechanical stopper



More information, including CAD data can be found at: www.epson.com/robots

Top view standard





Detail of S: position of the calibration points for the 3rd and 4th axis

Epson SCARA G3: It's all in the curve

The SCARA G3 has a small footprint with a large working area. And because many assembly tasks can only be performed in one arm orientation, we've developed the Epson G3 series with a curved arm to the left or right. This ergonomic feature allows the maximum square working area to be increased by up to 40%.

| Epson SCARA | | G3-301S, G3-301S-L, G3-251 S G3-301S-R | | G3-351S, G3-351S-L, G3-351S-R | |
|--------------------|---|--|--|---|--|
| Design | | Outw | vardly oriented horizontal articulated | d arm | |
| Load capacity | , | 1/3 kg no | om./max. | 1/3 kg nom./max. | |
| Range | Horizontal (J1+J2) Vertical (J3) Orientation (J4) | 250 mm (120+130) 150 or 120 mm (cleanroom) +/-360° | 300 mm (170+130) 150 or 120 mm (cleanroom) +/-360° | 350 mm (220 +130) 150 or 120 mm (cleanroom) +/-360° | |
| Repeatability | Horizontal (J1+J2) Vertical (J3) Orientation (J4) | +/-0.008 mm +/-0.010 mm +/-0.005° | +/-0.010 mm +/-0.010 mm +/-0.005° | +/-0.010 mm +/-0.010 mm +/-0.005° | |
| Moment of ine | ertia | 0.005/0.05 kg m² nom./max. | 0.005/0.05 kg m² nom./max. | 0.005/0.05 kg *m ² nom./max. | |
| User cabling | | Electrical: connection for 1x 15-pin D-Sub connector Pneumatic: connections for compressed air supply (1 x Ø 4 mm and 2 x Ø 6 mm) | | | |
| Z-axis | | Ø 16 mm, H 7 mm/11 mm outer/inner | | | |
| Insertion force |) | Permanent 150 (N) | | | |
| Weight | | 14 kg | | | |
| Controller | | RC700-A | | | |
| Manipulator design | | Mounting option for floor cleanroom (ISO3) & ESD | Mounting option for floor, Multimount | | |
| Available optic | ons | Extended power and | d signal cable (5m/10m/20m), be | ellows, Force Sensor | |

What's included:

Epson robot and controller Epson RC+ program CD including simulator Mounting bracket for the robot controller 70g grease for Z-axis 3m motor and signal cable Plug for emergency stop Plug for standard inputs and outputs Plug set for user cabling USB programming cable CD manuals Installation/safety manual

Manipulator options:

Extended power and signal cable (5m/10m/20m)

Tool adapter for easy installation of end effectors on Z-axis

Bellows option for mounting on Z-axis to protect the spindle and the environment from contamination

Epson Force Sensor for maximum precision in force-controlled applications





Epson SCARA G3 dimensions

| | G3-251S | G3-301S | G3-351S |
|---|-------------|-------------|-------------|
| А | 120 mm | 170 mm | 220 mm |
| В | 545 mm max. | 575 mm max. | 595 mm max. |

Working range, Epson SCARA G3

Top view standard



Top view curved



| | G3-251S | G3-301S | G3-351S | G3-301S-L | G3-301S-R | G3-351S-L | G3-351S-R |
|-----|---------|----------|----------|-----------|-----------|-----------|-----------|
| а | 120 mm | 170 mm | 220 mm | 170 mm | 170 mm | 220 mm | 220 mm |
| b-a | 130 mm | 130 mm | 130 mm | 130 mm | 130 mm | 130 mm | 130 mm |
| С | 84 mm | 104.8 mm | 142.3 mm | 120.7 mm | 120.7 mm | 191.6 mm | 191.6 mm |
| c1 | - | _ | - | 86.8 mm | 86.8 mm | 100.3 mm | 100.3 mm |
| d | 140° | 140° | 140° | 150° | 125° | 165° | 110° |
| d1 | - | - | - | 125° | 150° | 110° | 165° |
| е | 141° | 142° | 142° | 150° | 135° | 165° | 120° |
| e1 | - | - | - | 135° | 150° | 120° | 165° |
| f | 79.3 mm | 96.2 mm | 134.2 mm | 79.5 mm | 79.5 mm | 97 mm | 97 mm |
| f1 | - | - | - | 113.2 mm | 113.2 mm | 183 mm | 183 mm |

a Length of the 1st armb Length of the 2nd arm

c, c1 Working range d, d1 Working range of the 1st axis e, e1 Working range of the 2nd axis

f, f1 Range of the mechanical stopper





This and other information, including CAD data can be found at: www.epson.com/robots

Epson SCARA G6: The efficiency class

Thanks to its unique design, the SCARA G6 can perform tasks that usually require a 600mm arm length with an arm length of just 550mm. Ideally suited to applications in which high speed and maximum precision are required, such as mechanical production and electrical components, pick-and-place applications, small component placement, dosing and feeding.



the environment from contamination

applications

Epson Force Sensor for maximum precision in force-controlled

USB programming cable

CD manuals

Installation/safety manual



Epson SCARA G6 dimensions

Side view

| | G6-45xS | G6-55×S | G6-65×S |
|---|---------|---------|----------|
| А | 200 mm | 300 mm | 400 mm |
| | | G6-XX1S | G6-XX3+S |
| В | - | 300 mm | 330 mm |
| С | - | 119 mm | -31 mm |
| D | - | 684 mm | 834 mm |



Working range, Epson SCARA G6

| | | G6-45xS | G6-55×S | G6-65×S | |
|-----|-----------------|----------|-------------|-----------|--|
| а | - | 200 mm | 300 mm | 400 mm | |
| b-a | - | 250 mm | 250 mm | 250 mm | |
| - | Z: 0 to -270 | 134.8 mm | 161.2 mm | 232 mm | |
| С | | 143.5 mm | 101.2 11111 | 202 11111 | |
| d | - | 152° | 152° | 152° | |
| _ | Z: 0 to -270 | 147.5° | 117 50 | 117 50 | |
| е | Z: -270 to -330 | 145° | 147,5° | 147,5° | |
| f | - | 124.4 mm | 133.8 mm | 207.5 mm | |

In the Z-range: 0 to -270 mm, the range is limited by the collision area of the manipulator body and the arm.

- a Length of the 1st arm
- d Working range of the 1st axis
- b Length of the 2nd arm
- e Working range of the 2nd axis
- c Working range
- f Range of the mechanical stopper

Working range, Epson SCARA G6



This and other information, including CAD data can be found at: www.epson.com/robots

Top view standard





Epson SCARA G10: Fast and powerful

Featuring a solid, stiff arm, the Epson SCARA G10 impresses with ultra-fast speeds and high load capacities. The compact G10 is designed for applications such as the assembly of heavy components, packaging, palletising, loading and unloading.

| Epson SCARA | | G10-65xS | | G10-85×S | | |
|---------------------------|---|---|---|---|--|--|
| Design | | | Outwardly oriented horizontal articulated arm | | | |
| Load capacity | / | 5/10 kg nom./max. | | | | |
| | Horizontal (J1+J2) | 650 n | nm (250+400) | 850 mm (450 +400) | | |
| Range | Vertical (J3) | | | eanroom, IP54 and IP65) eanroom, IP54 and IP65) | | |
| | Orientation (J4) | | +/-360° | +/-360° | | |
| Repeatability | Horizontal (J1+J2) Vertical (J3) Orientation (J4) | +/- | -0.025 mm -0.010 mm -/-0.005° | +/-0.025 mm +/-0.010 mm +/-0.005° | | |
| Moment of ine | ertia | 0.02/0.25 | 5 kg m² nom./max. | 0.02/0.25 kg m ² nom./max. | | |
| User cabling | | | | bin and 1x 9-pin D-Sub connectors d air supply (1 x Ø 4 mm and 2 x Ø 6 mm) | | |
| Z-axis | | Ø 25 mm, H 7 mm/18 mm outer/inner | | | | |
| Insertion force | | Permanent 250 (N) | | | | |
| Weight | | 46 kg floor 46 kg ceiling 51 kg wall | | 48 kg floor 48 kg ceiling 53 kg wall | | |
| Controller | | RC700-A | | | | |
| Manipulator d | lesign | Mounting option for floor, wall, ceiling, cleanroom (ISO3) & ESD, IP Protection class: Standard/IP54/IP65 | | | | |
| Available optio | ons | Extended power and signal cable (5m/10m/20 m), tool adapter, for floor and ceiling mounting: cable outlet directly below or above the base (power/signal cable and user cabling), external wiring unit, bellows, Force Sensor | | | | |
| What's inclu | ided: | | Manipulator options: | | | |
| Epson robot | and controller | | Extended power and signal cable (5m/10m/20m) | | | |
| Epson RC+ p | orogram CD includi | ng simulator | Tool adapted for easy installation of end effectors on Z-axis | | | |
| Mounting bra | acket for the robot o | controller | | external empty conduit enables | | |
| 70g grease for Z-axis | | the clean supply of addit (recommended for fluid li | ional user media to each end effector ines) | | | |
| 3m motor and signal cable | | Υ. | v motor and signal lines to be fed through | | | |
| Plug for emergency stop | | a hole in the mounting plate so cables are not visible in the robot | | | | |
| Plug for stand | dard inputs and ou | tputs | cell (ideal for cleanroom | | | |
| Plug set for u | iser cabling | | Bellows option for mount environment from contar | ting on Z-axis to protect the spindle and the nination | | |
| | analman a a la la | | | | | |

applications

Epson Force Sensor for maximum precision in force-controlled

USB programming cable

CD manuals

Installation/safety manual



Epson SCARA G10 dimensions

Side view

| | G10-65xS | G10-85xS | G10-XX1S | G10-XX4S |
|---|----------|----------|----------|-----------|
| А | 250 mm | 450 mm | - | - |
| В | - | _ | 180 mm | 420 mm |
| С | - | - | 813.5 mm | 1053.5 mm |
| D | _ | _ | 213.5 mm | -26.5 mm |



Working range, Epson SCARA G10

| | G10-65xS | G10-85xS | |
|-----|----------|----------|--|
| а | 250 mm | | 450 mm |
| b-a | 400 mm | 400 mm | |
| С | 212.4 mm | | 207.8 mm |
| d | 152° | | 152° |
| е | 152.5° | | 152.5° |
| f | 199.4 mm | | 183.3 mm |
| 9 | | e W | orking range of the 1st axis orking range of the 2nd axis ange of the mechanical stopper |

Top view standard



Working range, G10-65 x S



More information, including CAD data can be found at: www.epson.com/robots



Epson SCARA G20: Extended arm with mighty strength

EPSON

The Epson SCARA G20 is suitable for very high loads with a weight of up to 20kg. An arm length of 1,000 or 850mm ensures that a large working area is covered. Due to the high moment of inertia of the U-axis, heavy loads can be moved quickly and reliably – without vibrations of the robot's arm that is often found with many competing models with a similar arm length.

| Epson SCARA | | G20-85xS | | G20-A0×S | |
|--------------------------------------|---|---|---|---|--|
| Design | Design | | Outwardly oriented horizontal articulated arm | | |
| Load capacity | / | | 10/20 kg | nom./max. | |
| | Horizontal (J1+J2) | 850 mm (450+400) | | 1000 mm (600+400) | |
| Range | Vertical (J3) | | | eanroom, IP54 and IP65) eanroom, IP54 and IP65) | |
| | Orientation (J4) | | +/-360° | +/-360° | |
| Repeatability | Horizontal (J1+J2) Vertical (J3) Orientation (J4) | +/- | -0.025 mm -0.010 mm -/-0.005° | +/-0.025 mm +/-0.010 mm +/-0.005° | |
| Moment of ine | ertia | 0.05/0.45 | kg*m² nom./max. | 0.05/0.45 kg * m² nom./max. | |
| User cabling | | | | oin and 1x 9-pin D-Sub connectors d air supply (1 x Ø 4 mm and 2 x Ø 6 mm) | |
| Z-axis | | | Ø 25 mm, H 7 mm | n/18 mm outer/inner | |
| Insertion force | | | Permane | ent 250 (N) | |
| Weight | | 48 kg floor 48 kg ceiling 53 kg wall | | 50 kg floor 50 kg ceiling 55 kg wall | |
| Controller | | RC700-A | | | |
| Manipulator d | esign | Mounting option for floor, wall, ceiling, cleanroom (ISO3) & ESD, IP Protection class: Standard/IP54/IP65 | | | |
| Available optic | ons | Extended power and signal cable (5 m/10 m/20 m), tool adapter, for floor and ceiling mounting: cable outlet directly below or above the base (power/signal and user cabling), external wiring unit, bellows, Force Sensor | | ctly below or above the base (power/signal cable | |
| What's inclu | ded: | | Manipulator options: | | |
| Epson robot a | and controller | | Extended power and sig | nal cable (5m/10m/20m) | |
| Epson RC+ p | orogram CD includi | ng simulator | Tool adapted for easy ins | stallation of end effectors on Z-axis | |
| Mounting bra | cket for the robot o | controller | | external empty conduit enables the | |
| 70g grease fo | or Z-axis | | (recommended for fluid li | al user media to each end effector ines) | |
| 3m motor and | d signal cable | | Υ. | v motor and signal lines to be fed through | |
| Plug for emergency stop | | | a hole in the mounting pl | ate so cables are not visible in the robot | |
| Plug for standard inputs and outputs | | tputs | cell (ideal for cleanroom | | |
| Plug set for user cabling | | | the environment from co | ting on Z-axis to protect the spindle and ntamination | |
| USB program | nming cable | | | maximum precision in force-controlled | |
| Installation/sa | afety manual | | -1-2-1-2-1-2-1-2-1-2-1-2-1-2-1-2-1-2-1- | | |

Epson SCARA G20 dimensions

Front view

| | G20-85xS | G20-A0xS | G20-XX1S | G20-XX4S |
|---|----------|----------|----------|-----------|
| А | 450 mm | 600 mm | - | - |
| В | - | - | 180 mm | 420 mm |
| С | - | - | 813.5 mm | 1053.5 mm |
| D | - | - | 213.5 mm | -26.5 mm |



Working range, Epson SCARA G20

| | G20-85xS | G20-A0xS | |
|-----|----------|---------------------------------|--|
| а | 450 mm | 600 mm | |
| b-a | 400 mm | 400 mm | |
| С | 207.8 mm | 307 mm | |
| d | 152° | 152° | |
| е | 152.5° | 152.5° | |
| f | 183.3 mm | 285.4 mm | |
| - | | d Working range of the 1st axis | |

b Length of the 2nd arm

c Working range

- e Working range of the 2nd axis
- f Range of the mechanical stopper

Top view standard



Working range, G20-85 x S



More information, including CAD data can be found at: www.epson.com/robots



Simulation of robot cells

Good preparation is everything. Plan and visualise all procedures in your production, validate your program offline initially and carry out troubleshooting and editing work easily from your desk. With the Epson RC+ Simulator – included in the software package – you save time and money through all phases of your project.

Phase 1 Design

Plan your robot cell at full size in advance and work out the expected cycle time for your application to check feasibility before a single part for the system has been made. Plan future system expansions in the simulation system to keep downtime to a minimum.

Phase 2 Integration

Completing the program validation process before the robots are delivered enables you to create programs at the same time, with the system capable of displaying and evaluating even complex motions. Collision risks are identified and equipment damage is prevented.

Phase 3 Operation and maintenance

Troubleshoot and modify programs from your desk. Use the 3D layout to visualise collision detection, reachability checks and robot motions.



Even simpler designs using the CAD-to-Point function

The CAD-to-Point function allows CAD data to be converted into robot points.



About Epson

Epson Robotic Solutions is one of the leading suppliers of high tech robot systems that are renowned worldwide for their reliability. The product range includes six-axis robots, SCARA robots, the SCARA entry-level LS and T models, the special Epson-developed Spider and N2 robots types, as well as the pioneering Dual Arm robot. Added to this are image processing controls and the Epson Force Sensor for force-controlled applications.

This gives Epson Robotic Solutions one of the most comprehensive ranges of high-precision industrial robots in the world, making them a technological pioneer for intelligently controlled automation processes.

Technological pioneer

1982

Epson SCARA robots freely available in Japan for the first time

1986

First class 1 cleanroom robot

1997 First PC-based controller

2008

Inventor of the right or left arm-optimised G3 SCARA robot

2009

Inventor of the spider – a unique SCARA robot with no dead zones

2013

First application of Epson QMEMS[®] sensors in robotics, reducing six-axis kinematics vibrations

2014

Epson Compact Vision CV2: Epson's own ultra-fast image processing computer

2016

Epson N2 series: World's first six-axis robot with folding arm - extremely compact and space-saving

2017

Epson Dual Arm robot with an arm geometry inspired by human physiology, as well as integrated sensors such as cameras, force sensors, and accelerometers

Pre- and after-sales support

Feasibility studies for maximum planning and project security

Support for planning and implementation

Introductory seminars, programming/maintenance courses, operator training

Inspection and individual maintenance concepts

Hotline service, on-site repair service

Central spare part stocking

Epson Industrial Solutions Center – find your solution









Experience all our Epson robots in action. Build, simulate and improve your automation application in a workshop cell, with help from our experts. The cell can be controlled and networked using all conventional fieldbus systems. In addition, we can supply you with modern peripherals such as a vision and conveyor tracking system.

Make an appointment

Call us on +49 2159 538 1800

or send an email to info.rs@epson.de

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